

## **ATTACHMENT B**

### **AMENDED PARAGRAPH PAGE 8 SHOWING AMENDMENTS**

One possible embodiment of the rotational control mechanism (124) is an over-center mechanism depicted in Figure 3. The over-center mechanism allows the handle to be at rest in only two positions, closed (104) or open (105) that are 90° apart. The rotation of an arm (140) is limited by stop points (130 & 132) that are secured to the frame of the holder. The opposite end of arm (140) rotates around shaft (108). A curved arm (134) is rotated about a pivot point at hinge pin (138) connected to arm (140). The opposite end of the curved arm (134) is tensioned by a spring (142) which is secured to a point on the frame of the holder (144). The spring ensures that the handle will only be in the opened or closed position by forcing the mechanism to rest against one of two stop points (130 & 132) thus stopping the travel of the arm (140) and limiting the rotation of the handle (103) to 90°. The over-center mechanism is just one of many possible means by which to control the position of the handle. Other mechanisms could be implemented that would limit the movement of the handle to specific locations.